

Move Valve

INVOCATION:
(! (POSITION VALVE \$X))

CONTEXT:
(AND (ALARM YES)
 (DELAY TWO-GOOD \$DEL-2TBS)
 (DELAY ONE-GOOD \$DEL-1TB))

EFFECTS:
((=> (POSITION VALVE \$X)))

DOCUMENTATION:
"This KA tries to put the valve in position \$x.
It waits (\$del-2tbs) time units if the two
sensors are good, or (\$del-1tb) time units
if only one is good.
After this time, it shutdowns if the trusted
sensor(s) is not in good position. "

